# A Online Supplement

## A.1 Proofs

The notation employed here is taken from Subsection 2.1. Lemma A.1 is preparatory for the proof of Theorem 1.

**Lemma A.1.** Let  $\boldsymbol{\varepsilon}$  be a unit variance white noise. The Hilbert space  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  decomposes into the orthogonal sum  $\mathcal{H}_t(\boldsymbol{\varepsilon}) = \bigoplus_{j=1}^{\infty} \mathbf{R}^{j-1} \mathcal{L}_t^{\mathbf{R}}$ , where

$$\mathbf{R}^{j-1}\mathcal{L}_t^{\mathbf{R}} = \left\{ \sum_{k=0}^{+\infty} b_k^{(j)} \varepsilon_{t-k2^j}^{(j)} \in \mathcal{H}_t(\boldsymbol{\varepsilon}) : \quad b_k^{(j)} \in \mathbb{R} \right\}$$

and, for any  $j \in \mathbb{N}$  and  $t \in \mathbb{Z}$ ,  $\varepsilon_t^{(j)}$  is given by eq. (6).

Proof.  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  is a Hilbert subspace of  $L^2(\Omega, \mathcal{F}, \mathbb{P})$ , equipped with the inner product  $\langle A, B \rangle = \mathbb{E}[AB]$  for all  $A, B \in L^2(\Omega, \mathcal{F}, \mathbb{P})$ . We begin with showing that the scaling operator **R** is well-defined, linear and isometric on  $\mathcal{H}_t(\boldsymbol{\varepsilon})$ .

Consider any  $X = \sum_{k=0}^{\infty} a_k \varepsilon_{t-k}$  in  $\mathcal{H}_t(\boldsymbol{\varepsilon})$ , that is  $\|X\|^2 = \sum_{p=0}^{\infty} a_p^2 < +\infty$ . Then,

$$\|\mathbf{R}X\|^2 = \frac{1}{2} \sum_{k=0}^{+\infty} a_{\lfloor\frac{k}{2}\rfloor}^2 = \frac{1}{2} \sum_{p=0}^{+\infty} a_{\lfloor\frac{2p}{2}\rfloor}^2 + \frac{1}{2} \sum_{p=0}^{+\infty} a_{\lfloor\frac{2p+1}{2}\rfloor}^2 = \sum_{p=0}^{+\infty} a_p^2 = \|X\|^2$$

and this quantity is finite. As a result, **R** is a well-defined (and bounded) operator. The linearity of **R** is immediate. To prove that **R** is isometric, take any  $X = \sum_{k=0}^{\infty} a_k \varepsilon_{t-k}, \ Y = \sum_{h=0}^{\infty} b_h \varepsilon_{t-h}$  in  $\mathcal{H}_t(\boldsymbol{\varepsilon})$ . By the white-noise properties of  $\boldsymbol{\varepsilon}$ ,

$$\langle \mathbf{R}X, \mathbf{R}Y \rangle = \sum_{k=0}^{+\infty} \frac{a_{\lfloor \frac{k}{2} \rfloor}}{\sqrt{2}} \frac{b_{\lfloor \frac{k}{2} \rfloor}}{\sqrt{2}} = \frac{1}{2} \sum_{p=0}^{+\infty} a_{\lfloor \frac{2p}{2} \rfloor} b_{\lfloor \frac{2p}{2} \rfloor} + \frac{1}{2} \sum_{p=0}^{+\infty} a_{\lfloor \frac{2p+1}{2} \rfloor} b_{\lfloor \frac{2p+1}{2} \rfloor}$$
$$= \sum_{p=0}^{+\infty} a_p b_p = \langle X, Y \rangle.$$

As a result, **R** is an isometry on  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  and the Abstract Wold Theorem (i.e. Theorem 1.1 in Nagy et al. 2010) applies.

The Abstract Wold Theorem supplies the orthogonal decomposition  $\mathcal{H}_t(\boldsymbol{\varepsilon}) = \hat{\mathcal{H}}_t(\boldsymbol{\varepsilon}) \oplus \tilde{\mathcal{H}}_t(\boldsymbol{\varepsilon})$ , where

$$\hat{\mathcal{H}}_t(\boldsymbol{\varepsilon}) = \bigcap_{j=0}^{+\infty} \mathbf{R}^j \mathcal{H}_t(\boldsymbol{\varepsilon}), \qquad \tilde{\mathcal{H}}_t(\boldsymbol{\varepsilon}) = \bigoplus_{j=1}^{+\infty} \mathbf{R}^{j-1} \mathcal{L}_t^{\mathbf{R}}$$

and  $\mathcal{L}_t^{\mathbf{R}} = \mathcal{H}_t(\boldsymbol{\varepsilon}) \ominus \mathbf{R} \mathcal{H}_t(\boldsymbol{\varepsilon})$  is called *wandering subspace*.

In particular, we show that  $\hat{\mathcal{H}}_t(\boldsymbol{\varepsilon})$  is the null subspace. Indeed, the subspaces  $\mathbf{R}^j \mathcal{H}_t(\boldsymbol{\varepsilon})$  are made of linear combinations of innovations  $\boldsymbol{\varepsilon}_t$  with coefficients equal to each others  $2^j$ -by- $2^j$ :

$$\mathbf{R}^{j}\mathcal{H}_{t}(\boldsymbol{\varepsilon}) = \left\{ \sum_{k=0}^{+\infty} c_{k}^{(j)} \left( \sum_{i=0}^{2^{j}-1} \varepsilon_{t-k2^{j}-i} \right) \in \mathcal{H}_{t}(\boldsymbol{\varepsilon}) : \quad c_{k}^{(j)} \in \mathbb{R} \right\}.$$

As a result,  $\hat{\mathcal{H}}_t(\boldsymbol{\varepsilon})$  can just include variables as  $\sum_{h=0}^{\infty} c\varepsilon_{t-h}$  with  $c \in \mathbb{R}$ . These elements belong to  $\mathcal{H}_t(\varepsilon)$ , hence  $\sum_{k=0}^{\infty} c^2$  is finite and this is possible just in case c = 0. As a result,  $\hat{\mathcal{H}}_t(\boldsymbol{\varepsilon}) = \{0\}$  and  $\mathcal{H}_t(\boldsymbol{\varepsilon}) = \tilde{\mathcal{H}}_t(\boldsymbol{\varepsilon})$ .

We now focus on the subspace  $\tilde{\mathcal{H}}_t(\boldsymbol{\varepsilon})$ . As the orthogonal complement of  $\mathbf{R}\mathcal{H}_t(\mathbf{x})$  is the kernel of the adjoint operator  $\mathbf{R}^*$  (see, for example, Theorem 1, §6.6 in Luenberger 1968), we determine  $\mathbf{R}^*$ . Specifically,  $\mathbf{R}^* : \mathcal{H}_t(\boldsymbol{\varepsilon}) \longrightarrow \mathcal{H}_t(\boldsymbol{\varepsilon})$  is such that

$$\mathbf{R}^*: \quad \sum_{k=0}^{+\infty} a_k \varepsilon_{t-k} \quad \longmapsto \quad \sum_{k=0}^{+\infty} \frac{a_{2k} + a_{2k+1}}{\sqrt{2}} \varepsilon_{t-k}.$$

Indeed,  $\mathbf{R}^*$  is well-defined and the relation  $\langle \mathbf{R}X, Y \rangle = \langle X, \mathbf{R}^*Y \rangle$  holds for any  $X = \sum_{h=0}^{\infty} b_h \varepsilon_{t-h}$ ,  $Y = \sum_{k=0}^{\infty} a_k \varepsilon_{t-k}$  in  $\mathcal{H}_t(\boldsymbol{\varepsilon})$ , due to the white noise nature of  $\boldsymbol{\varepsilon}$ :

$$\langle \mathbf{R}X, Y \rangle = \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} \frac{b_{\lfloor \frac{h}{2} \rfloor}}{\sqrt{2}} a_k \langle \varepsilon_{t-h}, \varepsilon_{t-k} \rangle = \sum_{k=0}^{+\infty} b_{\lfloor \frac{k}{2} \rfloor} \frac{a_k}{\sqrt{2}} = \sum_{k=0}^{+\infty} b_k \frac{a_{2k} + a_{2k+1}}{\sqrt{2}}$$
$$= \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} b_h \frac{a_{2k} + a_{2k+1}}{\sqrt{2}} \langle \varepsilon_{t-h}, \varepsilon_{t-k} \rangle = \langle X, \mathbf{R}^*Y \rangle.$$

As for the kernel of  $\mathbf{R}^*$ , we prove that

$$\ker(\mathbf{R}^*) = \left\{ \sum_{k=0}^{+\infty} d_k^{(1)} \left( \varepsilon_{t-2k} - \varepsilon_{t-2k-1} \right) \in \mathcal{H}_t(\boldsymbol{\varepsilon}) : \quad d_k^{(1)} \in \mathbb{R} \right\}.$$

Take any element of  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  of the kind  $X = \sum_{k=0}^{\infty} d_k^{(1)}(\varepsilon_{t-2k} - \varepsilon_{t-2k-1})$  for some square-summable sequence of real numbers  $\{d_k^{(1)}\}_k$ . Such X can be rewritten as  $X = \sum_{h=0}^{\infty} a_h \varepsilon_{t-h}$  with  $a_{2k+1} = -a_{2k}$  for all  $k \in \mathbb{N}_0$ , that is  $a_{2k} + a_{2k+1} = 0$ . Therefore, by the expression of  $\mathbf{R}^*$ , we realize that  $\mathbf{R}^* X = 0$ . Thus,

$$\left\{\sum_{k=0}^{+\infty} d_k^{(1)} \left(\varepsilon_{t-2k} - \varepsilon_{t-2k-1}\right) \in \mathcal{H}_t(\boldsymbol{\varepsilon}) : \quad d_k^{(1)} \in \mathbb{R}\right\} \subset \ker(\mathbf{R}^*).$$
(23)

Conversely, consider  $X = \sum_{h=0}^{\infty} a_h \varepsilon_{t-h}$  in ker( $\mathbf{R}^*$ ). Since  $\mathbf{R}^* X = 0$  in the  $L^2$ -norm,  $\sum_{k=0}^{\infty} (a_{2k} + a_{2k+1})^2 = 0$ . As a consequence,  $a_{2k+1} = -a_{2k}$  for any  $k \in \mathbb{N}_0$  and we can write  $X = \sum_{k=0}^{\infty} d_k^{(1)} (\varepsilon_{t-2k} - \varepsilon_{t-2k-1})$  with  $d_k^{(1)} = a_{2k}$ . As a result, also the converse inclusion in (23) holds and

$$\mathcal{L}_t^{\mathbf{R}} = \ker(\mathbf{R}^*) = \left\{ \sum_{k=0}^{+\infty} b_k^{(1)} \varepsilon_{t-2k}^{(1)} \in \mathcal{H}_t(\boldsymbol{\varepsilon}) : \quad b_k^{(1)} \in \mathbb{R} \right\}.$$

In addition,

$$\mathbf{R}\mathcal{L}_{t}^{\mathbf{R}} = \left\{ \sum_{k=0}^{+\infty} b_{k}^{(2)} \varepsilon_{t-4k}^{(2)} \in \mathcal{H}_{t}(\boldsymbol{\varepsilon}) : \quad b_{k}^{(2)} \in \mathbb{R} \right\}$$

and, for any  $j \in \mathbb{N}$ ,

$$\mathbf{R}^{j-1}\mathcal{L}_t^{\mathbf{R}} = \left\{ \sum_{k=0}^{+\infty} b_k^{(j)} \varepsilon_{t-k2^j}^{(j)} \in \mathcal{H}_t(\boldsymbol{\varepsilon}) : \quad b_k^{(j)} \in \mathbb{R} \right\}.$$

As the case with  $j \in \mathbb{N}$  can be derived by induction, we focus on  $\mathbf{R}\mathcal{L}_t^{\mathbf{R}}$  and show that

$$\mathbf{R}\mathcal{L}_{t}^{\mathbf{R}} = \left\{ \sum_{k=0}^{+\infty} d_{k}^{(2)} \left( \varepsilon_{t-4k} + \varepsilon_{t-4k-1} - \varepsilon_{t-4k-2} - \varepsilon_{t-4k-3} \right) \in \mathcal{H}_{t}(\boldsymbol{\varepsilon}) : \quad d_{k}^{(2)} \in \mathbb{R} \right\}.$$
(24)

Consider any  $Y \in \mathbf{R}\mathcal{L}_t^{\mathbf{R}}$ . Since Y is the image of some  $X \in \mathcal{L}_t^{\mathbf{R}}$ , there exists a square-summable sequence of real numbers  $\{d_k^{(1)}\}_k$  such that

$$X = \sum_{k=0}^{+\infty} d_k^{(1)} \left( \varepsilon_{t-2k} - \varepsilon_{t-2k-1} \right), \qquad Y = \sum_{k=0}^{+\infty} \frac{d_k^{(1)}}{\sqrt{2}} \left( \varepsilon_{t-4k} + \varepsilon_{t-4k-1} - \varepsilon_{t-4k-2} - \varepsilon_{t-4k-3} \right).$$

As a result,  $\mathbf{R}\mathcal{L}_{t}^{\mathbf{R}}$  is included in the set in (24). Vice versa, take any  $Y = \sum_{k=0}^{\infty} d_{k}^{(2)} (\varepsilon_{t-4k} + \varepsilon_{t-4k-1} - \varepsilon_{t-4k-2} - \varepsilon_{t-4k-3})$  for some square-summable sequence of coefficients  $\{d_{k}^{(2)}\}_{k}$ . Then Y belongs to  $\mathbf{R}\mathcal{L}_{t}^{\mathbf{R}}$  too, because it is the image of  $X = \sum_{k=0}^{\infty} \sqrt{2} d_{k}^{(2)} (\varepsilon_{t-2k} - \varepsilon_{t-2k-1})$ , which belongs to  $\mathcal{L}_{t}^{\mathbf{R}}$ . Therefore, the characterization in (24) is assessed.  $\Box$ 

#### Proof of Theorem 1

*Proof.* By applying the Classical Wold Decomposition to the zero-mean, weakly stationary purely non-deterministic process  $\mathbf{x}$ , we find that  $x_t$  belongs to the Hilbert space  $\mathcal{H}_t(\boldsymbol{\varepsilon})$ , where  $\boldsymbol{\varepsilon}$  is the unit variance white noise of classical Wold innovations of  $\mathbf{x}$ . Importantly,  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  orthogonally decomposes as in Lemma A.1. By denoting  $g_t^{(j)}$ 

the orthogonal projections of  $x_t$  on the subspaces  $\mathbf{R}^{j-1} \mathcal{L}_t^{\mathbf{R}}$ , we find that  $x_t = \sum_{j=1}^{\infty} g_t^{(j)}$ , where the equality is in the  $L^2$ -norm. Then, by using the characterizations of subspaces  $\mathbf{R}^{j-1}\mathcal{L}_t^{\mathbf{R}}$ , for any scale  $j \in \mathbb{N}$  we find a square-summable sequence of real coefficients  $\{\beta_k^{(j)}\}_k$  such that eq. (9) holds. As a result, we are allowed to decompose the variable  $x_t$  as in eq. (5).

We now show i). As we can see in eq. (6), the process  $\varepsilon^{(j)}$  is an  $MA(2^j-1)$  with respect to the fundamental innovations  $\boldsymbol{\varepsilon}$ . In addition, the subprocess  $\{\varepsilon_{t-k2^{j}}^{(j)}\}_{k\in\mathbb{Z}}$  is weakly stationary. Indeed, since  $\varepsilon$  is a unit variance white noise, for any  $k \in \mathbb{Z}$ ,

$$\mathbb{E}\left[\left(\varepsilon_{t-k2^{j}}^{(j)}\right)^{2}\right] = \frac{1}{2^{j}}\mathbb{E}\left[\left(\sum_{i=0}^{2^{j-1}-1}\varepsilon_{t-k2^{j}-i} - \sum_{i=0}^{2^{j-1}-1}\varepsilon_{t-k2^{j}-2^{j-1}-i}\right)^{2}\right] = \frac{1}{2^{j}}\sum_{i=0}^{2^{j}-1}\mathbb{E}\left[\varepsilon_{t}^{2}\right] = 1.$$

Thus,  $\mathbb{E}[(\varepsilon_{t-k2^{j}}^{(j)})^{2}]$  is finite and it does not depend on k. Moreover,  $\mathbb{E}[\varepsilon_{t-k2^{j}}^{(j)}] = 0$  for any  $k \in \mathbb{Z}$  and the expectation does not depend on k. Finally, we analyse cross-moments in the support  $S_t^{(j)} = \{t - k2^j : k \in \mathbb{N}_0\}$ . By taking  $h \neq k$ ,

$$\begin{split} & \mathbb{E}\left[\varepsilon_{t-h2^{j}}^{(j)}\varepsilon_{t-k2^{j}}^{(j)}\right] = \frac{1}{2^{j}}\mathbb{E}\left[\left(\sum_{i=0}^{2^{j-1}-1}\varepsilon_{t-h2^{j}-i} - \sum_{i=0}^{2^{j-1}-1}\varepsilon_{t-h2^{j}-2^{j-1}-i}\right)\right) \\ & \cdot \left(\sum_{l=0}^{2^{j-1}-1}\varepsilon_{t-k2^{j}-l} - \sum_{l=0}^{2^{j-1}-1}\varepsilon_{t-k2^{j}-2^{j-1}-l}\right)\right] \\ & = \frac{1}{2^{j}}\left\{\sum_{i=0}^{2^{j-1}-1}\sum_{l=0}^{2^{j-1}-1}\mathbb{E}\left[\varepsilon_{t-h2^{j}-i}\varepsilon_{t-k2^{j}-l}\right] - \sum_{i=0}^{2^{j-1}-1}\sum_{l=0}^{2^{j-1}-1}\mathbb{E}\left[\varepsilon_{t-h2^{j}-i}\varepsilon_{t-k2^{j}-2^{j-1}-l}\right] \\ & - \sum_{i=0}^{2^{j-1}-1}\sum_{l=0}^{2^{j-1}-1}\mathbb{E}\left[\varepsilon_{t-h2^{j}-2^{j-1}-i}\varepsilon_{t-k2^{j}-l}\right] + \sum_{i=0}^{2^{j-1}-1}\sum_{l=0}^{2^{j-1}-1}\mathbb{E}\left[\varepsilon_{t-h2^{j}-2^{j-1}-l}\varepsilon_{t-k2^{j}-2^{j-1}-l}\right]\right\}. \end{split}$$

Since  $h \neq k$ , the sets of indices  $\{h2^j, \ldots, h2^j + 2^j - 1\}$  and  $\{k2^j, \ldots, k2^j + 2^j - 1\}$  are disjoint and so the last sums are null. Therefore,  $\mathbb{E}[\varepsilon_{t-h2^{j}}^{(j)}\varepsilon_{t-k2^{j}}^{(j)}] = 0$  for all  $h \neq k$ . As a result,  $\{\varepsilon_{t-k2^{j}}^{(j)}\}_{k\in\mathbb{Z}}$  is weakly stationary on  $S_{t}^{(j)}$  and it is a unit variance white

noise.

We now turn to ii). For any fixed scale  $j \in \mathbb{N}$ , since the variables  $\varepsilon_{t-k^{2j}}^{(j)}$  are orthonormal when k varies, the component  $g_t^{(j)}$  has a unique representation as in eq. (8). Thus, the coefficients  $\beta_k^{(j)}$  are uniquely defined and, clearly,  $\sum_{j=1}^{\infty} \sum_{k=0}^{\infty} (\beta_k^{(j)})^2$  is finite.

In order to find the explicit expression of coefficients  $\beta_k^{(j)}$ , we exploit the orthogonal

decompositions of  $\mathcal{H}_t(\boldsymbol{\varepsilon})$  at different scales  $J \in \mathbb{N}$ :

$$\mathcal{H}_t(oldsymbol{arepsilon}) = \mathbf{R}^J \mathcal{H}_t(oldsymbol{arepsilon}) \oplus igoplus_{j=1}^J \mathbf{R}^{j-1} \mathcal{L}^{\mathbf{R}}_t.$$

We call  $\pi_t^{(j)}$  the orthogonal projection of  $x_t$  on the subspace  $\mathbf{R}^j \mathcal{H}_t(\boldsymbol{\varepsilon})$  and we proceed inductively.

We start by the first decomposition  $x_t = \pi_t^{(1)} + g_t^{(1)}$  coming from scale J = 1, namely  $\mathcal{H}_t(\varepsilon) = \mathbf{R}\mathcal{H}_t(\varepsilon) \oplus \mathcal{L}_t^{\mathbf{R}}$ . By the definitions of elements in  $\mathbf{R}\mathcal{H}_t(\varepsilon)$  and  $\mathcal{L}_t^{\mathbf{R}}$ described in Lemma A.1, we set

$$\pi_t^{(1)} = \sum_{k=0}^{+\infty} \gamma_k^{(1)} \frac{\varepsilon_{t-2k} + \varepsilon_{t-(2k+1)}}{\sqrt{2}} = \sum_{k=0}^{+\infty} c_k^{(1)} \left( \varepsilon_{t-2k} + \varepsilon_{t-(2k+1)} \right),$$
$$g_t^{(1)} = \sum_{k=0}^{+\infty} \beta_k^{(1)} \varepsilon_{t-2k}^{(1)} = \sum_{k=0}^{+\infty} d_k^{(1)} \left( \varepsilon_{t-2k} - \varepsilon_{t-2k-1} \right)$$

for some sequences of coefficients  $\{c_k^{(1)}\}_k$  and  $\{d_k^{(1)}\}_k$ , or equivalently  $\{\gamma_k^{(1)}\}_k$  and  $\{\beta_k^{(1)}\}_k$ , to determine in order to have  $x_t = \pi_t^{(1)} + g_t^{(1)}$ , where we set  $\sqrt{2}c_k^{(1)} = \gamma_k^{(1)}$  and  $\sqrt{2}d_k^{(1)} = \beta_k^{(1)}$ . The expressions above may be rewritten as

$$x_t = \sum_{k=0}^{+\infty} \left\{ \left( c_k^{(1)} + d_k^{(1)} \right) \varepsilon_{t-2k} + \left( c_k^{(1)} - d_k^{(1)} \right) \varepsilon_{t-2k-1} \right\}.$$

However, from the Classical Wold Decomposition of  $\mathbf{x}$ ,

$$x_t = \sum_{k=0}^{+\infty} \left\{ \alpha_{2k} \varepsilon_{t-2k} + \alpha_{2k+1} \varepsilon_{t-2k-1} \right\}$$

with the same fundamental innovations  $\varepsilon_t$ . By the uniqueness of writing of the Classical Wold Decomposition, the two expressions for  $x_t$  must coincide. As a result,  $c_k^{(1)}$  and  $d_k^{(1)}$  are the solutions of the linear system

$$\begin{cases} c_k^{(1)} + d_k^{(1)} &= \alpha_{2k} \\ c_k^{(1)} - d_k^{(1)} &= \alpha_{2k+1} \end{cases}$$

that is,

$$c_k^{(1)} = \frac{\alpha_{2k} + \alpha_{2k+1}}{2}, \qquad \qquad d_k^{(1)} = \frac{\alpha_{2k} - \alpha_{2k+1}}{2}$$

and, in particular, we find

$$\gamma_k^{(1)} = \frac{\alpha_{2k} + \alpha_{2k+1}}{\sqrt{2}}, \qquad \beta_k^{(1)} = \frac{\alpha_{2k} - \alpha_{2k+1}}{\sqrt{2}}.$$

Next, we focus on the scale J = 2. We exploit the decomposition of the space  $\mathbf{R}\mathcal{H}_t(\boldsymbol{\varepsilon}) = \mathbf{R}^2\mathcal{H}_t(\boldsymbol{\varepsilon}) \oplus \mathbf{R}\mathcal{L}_t^{\mathbf{R}}$  that implies the relation  $\pi_t^{(1)} = \pi_t^{(2)} + g_t^{(2)}$ . We follow the same track as in the previous case, by using the features of elements in  $\mathbf{R}^2\mathcal{H}_t(\boldsymbol{\varepsilon})$  and in  $\mathbf{R}\mathcal{L}_t^{\mathbf{R}}$  and, finally, by comparing the expression of  $\pi_t^{(2)} + g_t^{(2)}$  with the (unique) writing of  $\pi_t^{(1)}$  that we found before. Since

$$\pi_t^{(2)} = \sum_{k=0}^{+\infty} \gamma_k^{(2)} \frac{\varepsilon_{t-4k} + \varepsilon_{t-(4k+1)} + \varepsilon_{t-(4k+2)} + \varepsilon_{t-(4k+3)}}{2}, \qquad g_t^{(2)} = \sum_{k=0}^{+\infty} \beta_k^{(2)} \varepsilon_{t-4k}^{(2)},$$

by solving a simple linear system we discover that

$$\gamma_k^{(2)} = \frac{\alpha_{4k} + \alpha_{4k+1} + \alpha_{4k+2} + \alpha_{4k+3}}{2}, \qquad \beta_k^{(2)} = \frac{\alpha_{4k} + \alpha_{4k+1} - \alpha_{4k+2} - \alpha_{4k+3}}{2}$$

At the generic scale J = j, we retrieve the expressions of  $\beta_k^{(j)}$  and  $\gamma_k^{(j)}$  of eq. (7) and (11), where  $\pi_t^{(j)}$  is defined in eq. (10).

Finally, we show iii). First, when t is fixed,  $\mathbb{E}[g_t^{(j)}g_t^{(l)}] = 0$  for all  $j \neq l$  because  $g_t^{(j)}$ and  $g_t^{(l)}$  are, respectively, the projections of  $x_t$  on the subspaces  $\mathbf{R}^{j-1}\mathcal{L}_t^{\mathbf{R}}$  and  $\mathbf{R}^{l-1}\mathcal{L}_t^{\mathbf{R}}$ that are orthogonal by construction. Now, consider any  $g_{t-m2^j}^{(j)}$  with  $m \in \mathbb{N}_0$ . Clearly,  $g_{t-m2^j}^{(j)}$  belongs to  $\mathbf{R}^{j-1}\mathcal{L}_{t-m2^j}^{\mathbf{R}}$  but, by the definition of  $g_t^{(j)}$ , we can write

$$g_{t-m2^{j}}^{(j)} = \sum_{k=0}^{+\infty} \beta_{k}^{(j)} \varepsilon_{t-(m+k)2^{j}}^{(j)} = \sum_{K=0}^{+\infty} \beta_{K}^{(j)} \varepsilon_{t-K2^{j}}^{(j)},$$

where  $\beta_K^{(j)} = 0$  if  $K = 0, \ldots, m-1$  and  $\beta_K^{(j)} = \beta_k^{(j)}$  if K = m+k for some  $k \in \mathbb{N}_0$ . As a result,  $g_{t-m2^j}^{(j)}$  belongs to  $\mathbf{R}^{j-1}\mathcal{L}_t^{\mathbf{R}}$ , too. Similarly, at scale l, taken any  $n \in \mathbb{N}_0$ , it is easy to see that  $g_{t-n2^l}^{(l)}$  belongs to  $\mathbf{R}^{l-1}\mathcal{L}_t^{\mathbf{R}}$ . Hence, the orthogonality of such subspaces guarantees that  $\mathbb{E}[g_{t-m2^j}^{(j)}g_{t-n2^l}^{(l)}] = 0$  for all  $j \neq l$  and  $m, n \in \mathbb{N}_0$ . As for the general requirement on  $\mathbb{E}[g_{t-p}^{(j)}g_{t-q}^{(l)}]$  for any  $j, l \in \mathbb{N}$  and  $p, q, t \in \mathbb{Z}$ ,

$$\mathbb{E}\left[g_{t-p}^{(j)}g_{t-q}^{(l)}\right] = \sum_{k=0}^{+\infty}\sum_{h=0}^{+\infty}\beta_{k}^{(j)}\beta_{h}^{(l)}\mathbb{E}\left[\varepsilon_{t-p-k2^{j}}^{(j)}\varepsilon_{t-q-h2^{l}}^{(l)}\right]$$
$$= \frac{1}{\sqrt{2^{j+l}}}\sum_{k=0}^{+\infty}\sum_{h=0}^{+\infty}\beta_{k}^{(j)}\beta_{h}^{(l)}\sum_{u=0}^{2^{j-1}-1}\sum_{v=0}^{2^{l-1}-1}\left\{\mathbb{E}\left[\varepsilon_{t-p-k2^{j}-u}\varepsilon_{t-q-h2^{l}-v}\right] - \mathbb{E}\left[\varepsilon_{t-p-k2^{j}-u}\varepsilon_{t-q-h2^{l}-v}\right] - \mathbb{E}\left[\varepsilon_{t-p-k2^{j}-2^{j-1}-u}\varepsilon_{t-q-h2^{l}-v}\right] - \mathbb{E}\left[\varepsilon_{t-p-k2^{j}-2^{j-1}-u}\varepsilon_{t-q-h2^{l}-v}\right] + \mathbb{E}\left[\varepsilon_{t-p-k2^{j}-2^{j-1}-u}\varepsilon_{t-q-h2^{l}-2^{l-1}-v}\right]\right\}$$

and so

$$\begin{split} \mathbb{E}\left[g_{t-p}^{(j)}g_{t-q}^{(l)}\right] &= \frac{1}{\sqrt{2^{j+l}}}\sum_{k=0}^{+\infty}\sum_{h=0}^{+\infty}\beta_k^{(j)}\beta_h^{(l)}\sum_{u=0}^{2^{j-1}-1}\sum_{v=0}^{2^{l-1}-1}\left\{\gamma(p-q+k2^j+u-h2^l-v)\right.\\ &\quad -\gamma(p-q+k2^j+u-h2^l-2^{l-1}-v)\\ &\quad -\gamma(p-q+k2^j+2^{j-1}+u-h2^l-v)\\ &\quad +\gamma(p-q+k2^j+2^{j-1}+u-h2^l-2^{l-1}-v)\right\},\end{split}$$

where coefficients  $\beta_k^{(j)}$ ,  $\beta_h^{(l)}$  do not depend on t and  $\gamma$  denotes the autocovariance function of  $\boldsymbol{\varepsilon}$ . After the summations over u, v and k, h, the one remaining variables are j, l, p - q. In other words,  $\mathbb{E}[g_{t-p}^{(j)}g_{t-q}^{(l)}]$  depends at most on j, l, p - q.

### Proof of Theorem 2

*Proof.* First, we show that any process  $\mathbf{g}^{(j)}$  is well-defined. Indeed, by using the moving average representation of each  $g_t^{(j)}$  with respect to the innovations on the support  $S_t^{(j)}$  and the definition of detail processes  $\boldsymbol{\varepsilon}^{(j)}$ , we have

$$g_{t}^{(j)} = \sum_{k=0}^{+\infty} \beta_{k}^{(j)} \varepsilon_{t-k2^{j}}^{(j)} = \sum_{k=0}^{+\infty} \sum_{i=0}^{2^{j}-1} \beta_{k}^{(j)} \delta_{i}^{(j)} \varepsilon_{t-k2^{j}-i} = \sum_{h=0}^{+\infty} \beta_{\lfloor \frac{h}{2^{j}} \rfloor}^{(j)} \delta_{h-2^{j} \lfloor \frac{h}{2^{j}} \rfloor}^{(j)} \varepsilon_{t-h}, \qquad (25)$$

where  $h = k2^j + i$ ,  $k = \lfloor \frac{h}{2^j} \rfloor$  and  $i = h - 2^j \lfloor \frac{h}{2^j} \rfloor$ . Condition (13) ensures the square-summability of the coefficients and so each  $\mathbf{g}^{(\mathbf{j})}$  is well-defined.

In addition, the process **x** is well-defined because of Conditions (13) and (14). According to the latter, the components  $g_t^{(j)}$  are orthogonal to each others at different scales for fixed  $t \in \mathbb{Z}$ . Therefore,

$$\mathbb{E}\left[x_t^2\right] = \mathbb{E}\left[\left(\sum_{j=1}^{+\infty} g_t^{(j)}\right)^2\right] = \sum_{j=1}^{+\infty} \mathbb{E}\left[\left(g_t^{(j)}\right)^2\right] = \sum_{j=1}^{+\infty} \sum_{h=0}^{+\infty} \left(\beta_{\lfloor \frac{h}{2^j} \rfloor}^{(j)} \delta_{h-2^j \lfloor \frac{h}{2^j} \rfloor}^{(j)}\right)^2,$$

which is finite because of (13). In consequence, the process x is well-defined.

Now we show that  $\mathbf{x}$  is weakly stationary, with zero mean. We already observed that  $\mathbb{E}[x_t^2]$  is finite and not dependent on t. In addition, since the processes  $\mathbf{g}^{(j)}$  have zero mean,  $\mathbb{E}[x_t] = 0$  for any  $t \in \mathbb{Z}$ . Finally, take  $p \neq q$ . Then,

$$\mathbb{E}\left[x_{t-p}x_{t-q}\right] = \mathbb{E}\left[\left(\sum_{j=1}^{+\infty} g_{t-p}^{(j)}\right)\left(\sum_{l=1}^{+\infty} g_{t-q}^{(l)}\right)\right] = \sum_{j=1}^{+\infty} \sum_{l=1}^{+\infty} \mathbb{E}\left[g_{t-p}^{(j)}g_{t-q}^{(l)}\right].$$

As  $\mathbb{E}[g_{t-p}^{(j)}g_{t-q}^{(l)}]$  are dependent at most on j, l and p-q (see e.g. the computations in the proof of Theorem 1),  $\mathbb{E}[x_{t-p}x_{t-q}]$  depends at most on the difference p-q. As a result, **x** is weakly stationary, with zero mean.

By taking the sum over scales  $j \in \mathbb{N}$  in eq. (25), we obtain the decomposition of  $x_t$  with respect to the process  $\varepsilon$  stated in eq. (16). Clearly, **x** is purely nondeterministic.

Proposition A.1. The time series

$$\mathbf{R}x_t = \sum_{k=0}^{+\infty} \frac{\alpha_{\lfloor \frac{k}{2} \rfloor}}{\sqrt{2}} \varepsilon_{t-k} \qquad and \qquad \mathbf{R}_{\mathbf{x}}x_t = \frac{1}{\sqrt{2}} \left( x_t + x_{t-1} \right)$$

have spectral density functions, respectively,

$$f_{\mathbf{R}}(\lambda) = 2\cos^2\left(\frac{\lambda}{2}\right)f_x(2\lambda)$$
 and  $f_{\mathbf{R}_{\mathbf{x}}}(\lambda) = 2\cos^2\left(\frac{\lambda}{2}\right)f_x(\lambda),$ 

where  $f_x(\lambda)$  is the spectral density function of  $x_t$ .

*Proof.* Define the time-invariant linear filter  $A(\mathbf{L}) = \sum_{h=0}^{\infty} \alpha_h \mathbf{L}^h$ , so that  $x_t = A(\mathbf{L})\varepsilon_t$ .

Since  $\sum_{h=0}^{\infty} |\alpha_h| < +\infty$  and the spectral density function of  $\varepsilon_t$  is  $f_{\varepsilon}(\lambda) = 1/2\pi$ ,

$$f_x(\lambda) = \left| A\left(e^{-i\lambda}\right) \right|^2 f_\varepsilon(\lambda) = \left| \sum_{h=0}^{+\infty} \alpha_h e^{-ih\lambda} \right|^2 \frac{1}{2\pi}$$
$$= \frac{1}{2\pi} \left\{ \left( \sum_{h=0}^{+\infty} \alpha_h \cos(h\lambda) \right)^2 + \left( \sum_{h=0}^{+\infty} \alpha_h \sin(h\lambda) \right)^2 \right\}$$
$$= \frac{1}{2\pi} \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} \alpha_h \alpha_k \cos(\lambda(k-h)).$$

First, consider  $\mathbf{R}x_t$ . As  $\sum_{k=0}^{\infty} |\alpha_{\lfloor \frac{k}{2} \rfloor}| = 2 \sum_{h=0}^{\infty} |\alpha_h| < +\infty$ , we have

$$f_{\mathbf{R}}(\lambda) = \left| \sum_{k=0}^{+\infty} \frac{\alpha_{\lfloor \frac{k}{2} \rfloor}}{\sqrt{2}} e^{-ik\lambda} \right|^2 \frac{1}{2\pi} = \frac{1}{2\pi} \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} \frac{\alpha_{\lfloor \frac{h}{2} \rfloor} \alpha_{\lfloor \frac{k}{2} \rfloor}}{2} \cos(\lambda(k-h))$$
$$= \frac{1}{2\pi} \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} \alpha_h \alpha_k \left\{ \cos(2\lambda(k-h)) + \frac{\cos(\lambda(2k-2h+1)) + \cos(\lambda(2k-2h-1))}{2} \right\}$$
$$= \frac{1}{2\pi} \sum_{h=0}^{+\infty} \sum_{k=0}^{+\infty} \alpha_h \alpha_k \cos(2\lambda(k-h)) \left\{ 1 + \cos(\lambda) \right\} = 2\cos^2\left(\frac{\lambda}{2}\right) f_x(2\lambda).$$

Now consider  $\mathbf{R}_{\mathbf{x}} x_t$ . The spectral density function in the claim follows from

$$f_{\mathbf{R}_{\mathbf{x}}}(\lambda) = \left|\frac{1}{\sqrt{2}} \left(e^0 + e^{-i\lambda}\right)\right|^2 f_x(\lambda) = \frac{1}{2} \left\{ (1 + \cos(\lambda))^2 + \sin^2(\lambda) \right\} f_x(\lambda).$$

#### A.2 Forecasting from the persistence-based decomposition

We provide the formulas for conditional expectation and variance of a process  $\mathbf{x} = \{x_t\}_{t\in\mathbb{Z}}$  that has Classical and Extended Wold Decompositions given by eq. (4) and (5), respectively. We consider the filtration generated by the white noise  $\boldsymbol{\varepsilon} = \{\varepsilon_t\}_{t\in\mathbb{Z}}$  assuming that the innovations  $\varepsilon_t$  are independent.

Fix  $p \in \mathbb{N}$ . The conditional expectation at time t of  $x_{t+p}$  is characterized by an off-set of the classical Wold coefficients, namely  $\mathbb{E}_t[x_{t+p}] = \sum_{h=0}^{\infty} \alpha_{h+p} \varepsilon_{t-h}$ . Notably, such offset is inherited by the Extended Wold Decomposition of  $\mathbb{E}_t[x_{t+p}]$ :

$$\mathbb{E}_t \left[ x_{t+p} \right] = \sum_{j=1}^{+\infty} \sum_{k=0}^{+\infty} \beta_{k,p}^{(j)} \varepsilon_{t-k2^j}^{(j)},$$

where, for any  $j \in \mathbb{N}$  and  $k \in \mathbb{N}_0$ ,

$$\beta_{k,p}^{(j)} = \frac{1}{\sqrt{2^j}} \left( \sum_{i=0}^{2^{j-1}-1} \alpha_{k2^j+i+p} - \sum_{i=0}^{2^{j-1}-1} \alpha_{k2^j+2^{j-1}+i+p} \right).$$

Therefore, once the Extended Wold Decomposition of  $x_t$  is known, *p*-step ahead forecasts do not require a large additional effort because they are driven by the detail processes  $\varepsilon^{(j)}$  too and coefficients  $\beta_{k,p}^{(j)}$  are easily computed.

As to the conditional variance, the properties of the Classical Wold Decomposition ensure that  $\operatorname{Var}_t(x_{t+p}) = \alpha_0^2 + \cdots + \alpha_{p-1}^2$ . By Theorem 2 the coefficients  $\alpha_h$  can be obtained from the scale-specific  $\beta_k^{(j)}$  and so  $\operatorname{Var}_t(x_{t+p})$  can be derived directly from them. For example,  $\operatorname{Var}_t(x_{t+1}) = \alpha_0^2 = (\sum_{j=1}^{\infty} \beta_0^{(j)} / \sqrt{2^j})^2$ .